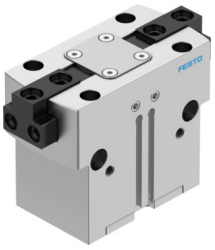
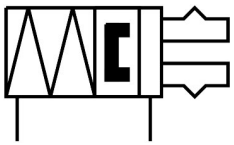
Parallel gripper
HGPT-35-A-B-F-G1

Part number: 560214





Data sheet

Feature	Value
Size	35
Stroke per gripper jaws	4 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax, ay	0.1 deg
Max. gripper jaw backlash Sz	0.02 mm
Rotationally symmetrical	0.2 mm
Repetition accuracy, gripper	0.05 mm
Number of gripper jaws	2
Drive system	Pneumatic
Mounting position	optional
Mode of operation	Double-acting
Gripper function	Parallel
Gripper force back-up	During opening
Design	Wedge-shaped drive Force pilot operated motion sequence
Position detection	Via proximity switch
Operating pressure	4 bar...8 bar
Operating pressure of blocked air	0 bar...0.5 bar
Max. operating frequency of gripper	3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	35 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	115 ms
Max. mass per external gripper finger	180 g
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	2 - Moderate corrosion stress
LABS (PWIS) conformity	VDMA24364-B1/B2-L
Degree of protection	IP40
Ambient temperature	5 °C...60 °C
Mass moment of inertia	3.974 kgcm²
Max. force on gripper jaw Fz static	1800 N
Max. torque at gripper Mx static	80 Nm

Feature	Value
Max. torque at gripper My static	60 Nm
Max. torque at gripper Mz static	50 Nm
Lubrication interval for guide components	5 MioCyc
Product weight	567 g
Type of mounting	Either: Via female thread and centring sleeve Via through-hole and centring sleeve Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection, blocked air	M5
Pneumatic connection	M5
Note on materials	RoHS-compliant
Material cover cap	High-alloy stainless steel
Material housing	Anodised aluminium
Material gripper jaws	Hardened steel